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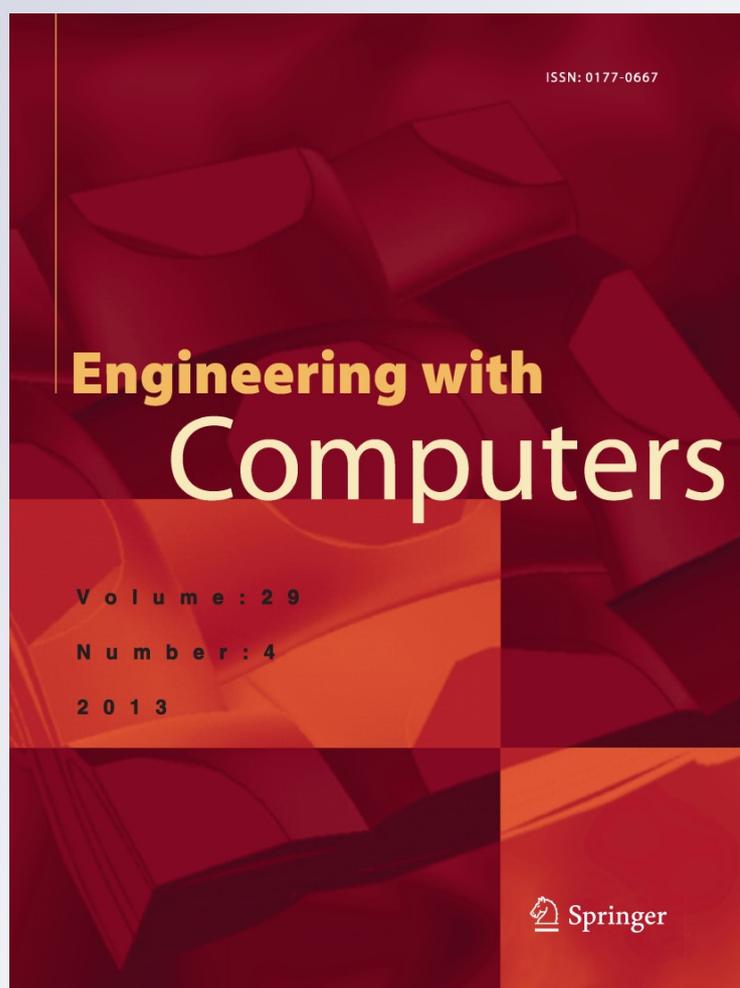
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# Performance of a flying cross bar to incapacitate a long-rod penetrator based on a finite element model

Yo-Han Yoo · Seung Hoon Paik · Jong-Bong Kim · Hyunho Shin

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**Abstract** Performance of a flying cross bar, instead of the flying plate, to incapacitate the long-rod penetrator, has been evaluated numerically based on a finite element model. The length to diameter ratio,  $L/D$ , of the penetrator was 30 and the velocity was 2.0 km/s. The length of the cross bar was fixed to  $0.5L$  and the velocity of the bar was determined from its mass and given kinetic energy. The bar was assumed to impact the mid point of the penetrator at  $45^\circ$  of obliquity. The efficiency of flying cross bar is maximum when the diameter of the bar is in the range between  $1D$  and  $4D$  depending on the energy of the bar and the distance to witness block. The protection capability of the bar has been discussed in terms of the shape and lateral displacement of the disturbed penetrator by the flying cross bar.

**Keywords** Flying cross bar · Long-rod penetrator · Active armour · Lateral disturbance

## 1 Introduction

As a method to protect a long-rod penetrator, single or dual flying plates are usually considered in active armour technology [1–7]. The flying plate is known to transfer lateral loads to the penetrator, which yields deflection, rotation, direction change, and breakage of the penetrator before reaching the main target behind the flying plate. Despite its known efficiency, flying a plate is never a simple task due to the excessive energy taken to fly the plate toward the incoming penetrator [8–10].

A flying cross bar, instead of a flying plate, has been recently considered, and its feasibility to incapacitate the long-rod penetrator has been reported by Liden et al. [11]. Employment of the flying cross bar is believed to be an efficient way to reduce the amount of energy required to fly an object. Provided its protection capability is proven, despite of its very light weight, the problem that has been long overdue is solved to fly it with a greatly reduced amount of energy. In order to exploit the performance of the flying cross bar for the design of a sensor-activated armour, examining the influence of the parameters such as the diameter and kinetic energy (velocity) of the bar on the performance to incapacitate the incoming penetrator is of importance. In this regard, the interaction characteristics of the flying cross bar with the long-rod projectile has been numerically investigated in the current work from the viewpoints of the required kinetic energy of the flying bar and the resultant depth of penetration in a witness block. It will be demonstrated that, at a given kinetic energy, the flying cross bar is strongly superior to the flying plate in defeating a long-rod penetrator.

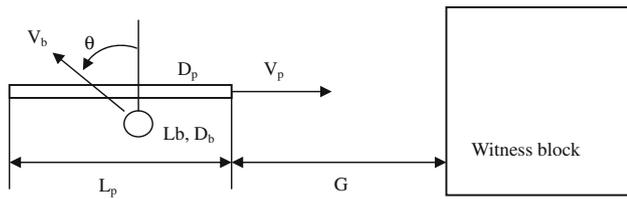
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**Fig. 1** Schematic cross-sectional view of the model

**Table 1** Velocity of bar (in m/s unit),  $V_b$ , at a given conditions of  $KE_b/KE_p$  and bar diameter ( $D_b$ )

$KE_b/KE_p$	1/128	1/64	1/32	1/16	1/8
$D_b = 1D_p$	373.9	528.7	747.7	1057.4	1495.4
$D_b = 1.5D_p$	249.2	352.5	498.5	705.0	997.0
$D_b = 2D_p$	186.9	264.4	373.9	528.7	747.7
$D_b = 3D_p$	124.6	176.2	249.2	352.5	498.5
$D_b = 4D_p$	93.5	132.2	186.9	264.4	373.9
$D_b = 5D_p$	74.8	105.7	149.5	211.5	299.1
$D_b = 6D_p$	62.3	88.1	124.6	176.2	249.2
$D_b = 7D_p$	53.4	75.5	106.8	151.1	213.6
$D_b = 8D_p$	46.7	66.1	93.5	132.2	186.9
$D_b = 9D_p$	23.4	33.0	46.7	66.1	93.5

**2 Numerical analysis**

Figure 1 shows the schematic cross-sectional view of the model. The length ( $L_p$ ) and the diameter ( $D_p$ ) of the penetrator were 150 and 5 mm, respectively ( $L_p/D_p = 30$ ). The velocity of penetrator ( $V_p$ ) was fixed to 2 km/s, and thus the kinetic energy of the penetrator (tungsten heavy alloy),  $KE_p$ , was fixed to  $1.037 \times 10^5$  J. An increased length of cross bar  $L_b$  would increase the probability of impact while increasing the mass. The length of flying cross bar ( $L_b$ ) was selected as  $0.5L_p$  ( $L_b = 75$  mm) in the present study. As the energy required to drive the cross bar is an important issue, the kinetic energy of the cross bar ( $KE_b$ ) was varied with reference to  $KE_p$ :  $KE_b/KE_p = 1/128, 1/64, 1/32, 1/16, 1/8$ . At each aimed  $KE_b$  value, the diameter of the cross bar ( $D_b$ ) was varied independently:  $D_b/D_p = 1, 1.5, 2, 3, 4, 5, 6, 7, 8, 16$ , where  $D_p$  is the diameter of the penetrator. An increased  $D_b$  yields decreased bar velocity at a given  $KE_b$ , as the length of the bar has been fixed. The velocity of the bar at given conditions of  $KE_b/KE_p$  and bar diameter ( $D_b$ ) is shown in Table 1. The cross bar was assumed to impact the middle of the penetrator at  $45^\circ$  of obliquity ( $\theta = 45^\circ$ ).<sup>1</sup> The witness block was 200 mm in height, 50 mm in width, and 250 mm in length.

<sup>1</sup> Hitting the midpoint of the penetrator would be rare in practical situation; The cases of hitting other points will be the subject of a future work.

The protection effectiveness generally increases as the distance to witness block from the location of impact increases since the residual penetrator may rotate, move laterally, and/or deform more as the flight time increases after it is disturbed by the cross bar. Thus, the distance to the witness block ( $G$ ) is also an important design parameter, which has been varied as,  $2L_p, 3L_p,$  and  $4L_p$ , in this study.

In order to consider strain-rate hardening as well as thermal softening in addition to the strain hardening considered in static deformation of metallic material, Johnson–Cook flow stress model [12] was used,

$$\sigma = (A + B\varepsilon^n) \left( 1 + C \ln \frac{\dot{\varepsilon}}{\dot{\varepsilon}_0} \right) \left[ 1 - \left( \frac{T - T_{ref}}{T_{melt} - T_{ref}} \right)^m \right] \quad (1)$$

Here,  $\sigma$  is flow stress,  $A$  the static yield strength,  $B$  the strain hardening parameter,  $\varepsilon$  the equivalent plastic strain,  $n$  the strain hardening exponent,  $C$  the strain rate parameter,  $\dot{\varepsilon}$  the equivalent plastic strain rate,  $\dot{\varepsilon}_0$  the reference strain rate,  $T$  the temperature,  $T_{ref}$  the reference temperature,  $T_{melt}$  the melting temperature and  $m$  the temperature exponent. The material of the penetrator is tungsten heavy alloy (DX2HCMF), while the cross bar and witness block are high hardness steel (SIS 2541-03), which properties are shown in Table 2 [13].

The equation of state (EOS) used herein is the polynomial model,

$$P = C_0 + C_1\mu + C_2\mu^2 + C_3\mu^3 + (C_4 + C_5\mu + C_6\mu^2)E \quad (2)$$

where,  $P$  is pressure and  $C_i$  are the coefficients.  $\mu = \rho/\rho_0 - 1$  and  $\rho/\rho_0$  is the ratio of density to initial density.  $E$  is the internal energy per unit volume. The value  $C_1$  used in this study has been 295 GPa for DX2HCMF and 167 GPa for SIS 2541-3. All other  $C_i$  parameters have been set to zero.  $C_1$  is, by itself, the elastic bulk modulus. Thus, the EOS has been reduced to the simplest form,  $P = C_1\mu$ .

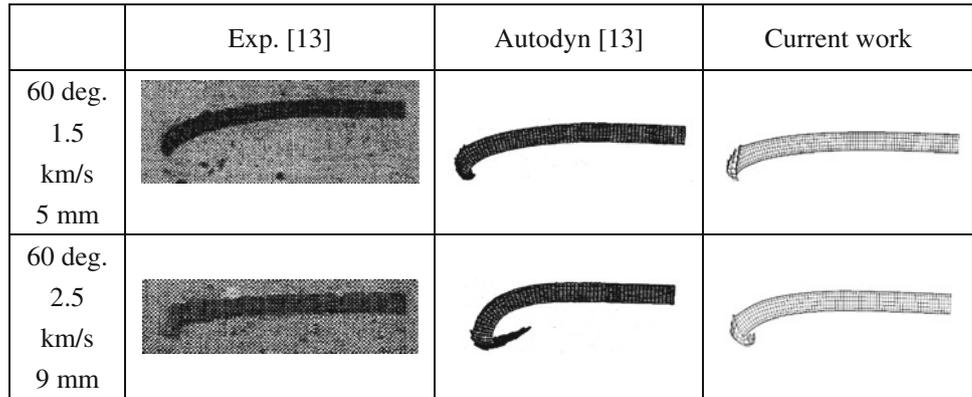
No fracture models were considered for both the penetrator and the bar, and thus any failure of the material by the current simulation is purely caused by the element erosion. As the tensile fracture with crack propagation is not replicated in the present work, actual performance could be different from the predicted results herein. Despite of this limitation, the current numerical results may be used to examine the sensitivity of performance to design parameters, and in general, the trends, rather than absolute values, will probably be correct.

Material erosion has been simulated by eliminating appropriate elements from the model during calculation when they reach a certain plastic strain limit. The empirical equivalent plastic strain limit of 1.5 is adopted in the current work based on a preliminary effort. The validity of the used strain limit together with adopting no fracture models will be checked in this section.

**Table 2** Material constants for the Johnson–Cook model [8]

Material	Density (kg/m <sup>3</sup> )	A (GPa)	B (GPa)	n	C	m	T <sub>ref</sub> (K)	T <sub>melt</sub> (K)
SIS2541-03	7,870	0.75	1.15	0.49	0.014	1.0	293	1,700
DX2HCMF	17,600	1.05	0.177	0.12	0.0275	1.0	293	1,723

**Fig. 2** Comparison of the deformed shapes of the residual penetrator between the current work and existing experimental/numerical results in Ref. [13]



**Table 3** Comparison of simulated length and velocity of residual penetrator with existing experiment in Ref. [13]

Oblique angle (°)	V <sub>o</sub> (km/s)	Plate thickness (mm)	Residual length (L/L <sub>o</sub> )			Residual velocity (V/V <sub>o</sub> )		
			Exp. [13]	Numerical [13]	Current work	Exp. [13]	Numerical [13]	Current work
60	1.5	5.0	0.85	0.87	0.84	0.97	0.98	0.97
	2.5	9.0	0.76	0.75	0.75	0.99	0.99	0.98

Only half of the three dimensional space was analyzed considering the symmetry of the model. In order to maintain a similar mesh size of the penetrator to the cross bar and witness block, a fine mesh with the size of 0.67 mm (as compared to  $D_p = 5$  mm) was modelled around the impact region of the witness block. Therefore, the total number of elements differed according to the size of the fine mesh region of the block, from ~200,000 to 300,000. A commercial finite element package, LS-DYNA [14], was used for the analysis. The basic element formulation, stress update method, time integration method, and contact-impact algorithm, etc., employed in the package, are described in Ref. [14].

Admitting the limitation of the current simulation in accounting for the tensile fracture mode with crack propagation, the generality (validity) of the current simulation itself was checked *first* by using two cases. The first case was the penetrator that was not fractured after impacting onto an oblique (60°) steel plate in an experiment [13]. The result of our simulation is shown in Fig. 2. Residual lengths and velocities of the penetrator are shown in Table 3. The diameter ( $D$ ) and length ( $L$ ) of the penetrator were 5 and 75 mm, respectively, resulting in an  $L/D$  ratio of 15. The thicknesses of the plate were 5 mm when the velocity of the penetrator was 1.5 km/s and 9 mm when 2.5 km/s. The

material behaviour was modelled using the Johnson–Cook viscoplastic model. The plate and the penetrator were the same materials as the current work (SIS 2541-03 and DX2HCMF, respectively). Based on Fig. 2 and Table 3,<sup>2</sup> the current simulation shows good agreement with the experimental data as well as the numerical analysis shown in Ref. [13].

The second case was the penetration event in the witness block, that does not involve the failure mode such as the crack-involved tensile fracture. The simulated depth of penetration  $P_o$  in the witness block by the undisturbed penetrator was compared with the existing values in the literature.  $P_o$  was 183.6 mm at the impact velocity of 2.0 km/s in our separate simulation, while it was 182.9 mm (Eq. 5 in Ref. [15]) or 176.1 mm (Eq. 12 in Ref. [16]) in the literature. The material of the penetrator in Refs. [15, 16] was a tungsten alloy; however, it was not exactly the same grade as that used in this study. Furthermore,  $P_o$  in Ref. [15] was the extrapolated value from approximate equation to the experiment up to 1.8 km/s of the penetrator velocity, while Ref. [16] was based on the approximate

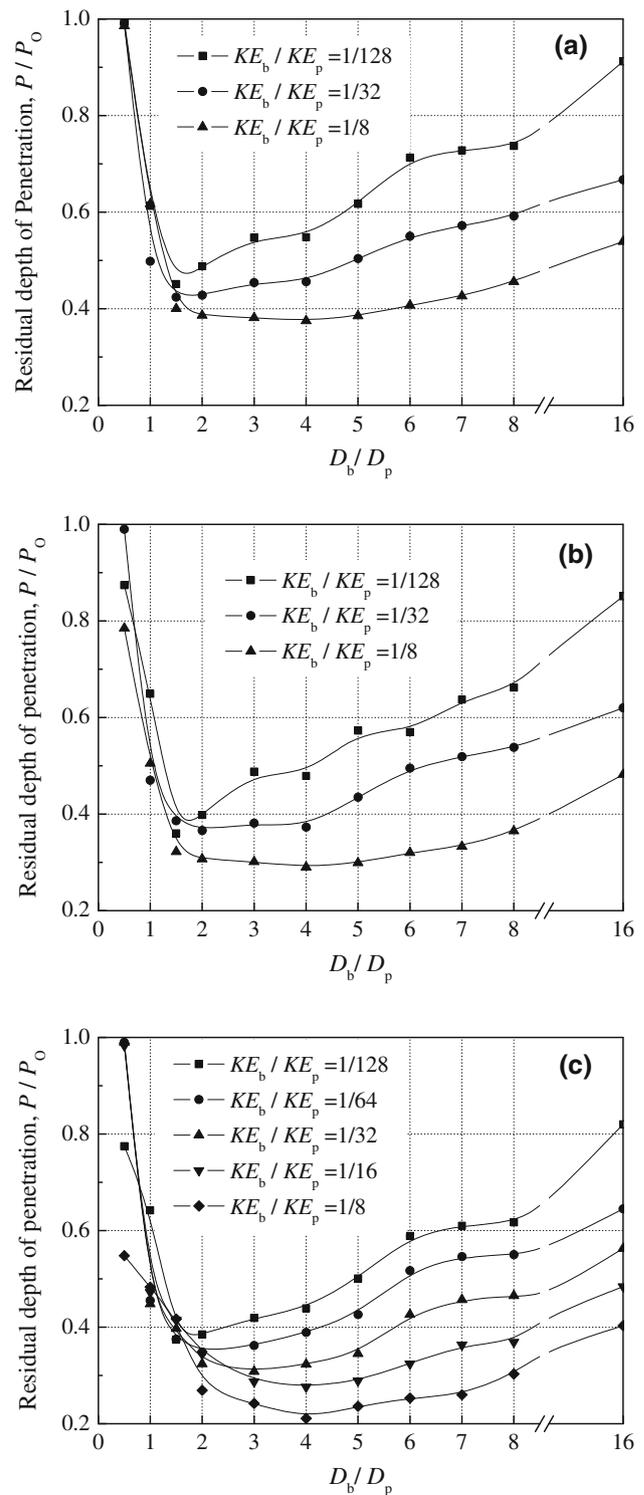
<sup>2</sup> In Table 3, the decrease of velocity after the impact is so small; The velocity ratio ( $V/V_o$ ) of 0.97~0.99 may be within the margin of errors.

equation to the simulation (by CTH code) from 1.5 to 4.5 km/s. Thus, the reliability of the simulation of the penetration process itself is ensured. However, the depth of penetration by the *deformed* penetrator after the interaction with the cross bar has a meaning on a comparative basis between the simulation cases because of the lack of the tensile-crack-involved fracture mode of the penetrator as mentioned before.

### 3 Results and discussion

Figure 3 shows the effects of  $KE_b/KE_p$ ,  $D_b/D_p$  and  $G$  on the normalized depth of penetration in witness block,  $P/P_o$ , by the disturbed residual penetrator.  $P_o$  is 183.6 mm as described previously. First of all, in all of the diagrams in Fig. 3, the protection efficiency,  $P/P_o$ , itself is superior (lower value) as the normalized kinetic energy of the cross bar  $KE_b/KE_p$ , increases, regardless of the normalized diameter of the bar,  $D_b/D_p$ , and distance to the witness block,  $G$ . As  $D_b/D_p$  increases,  $P/P_o$  initially decreases rapidly, but increases back after a minimum  $P/P_o$ . The  $D_b/D_p$  yielding minimum  $P/P_o$  generally shifts from 1.5 to 4.0 as the kinetic energy of the bar  $KE_b/KE_p$  increases. Interestingly, as the kinetic energy of the bar  $KE_b/KE_p$  grows larger, the relatively wider range of  $D_b/D_p$  shows the smaller depth of penetration. As for the influence of  $G$ , the overall trend of  $P/P_o$  in terms of  $D_b/D_p$  for varying  $KE_b/KE_p$  is maintained in a similar fashion. However, the  $P/P_o$  at a given condition decreases significantly with  $G$  since the penetrator deforms and rotates more as the flying time increases after the impact with the cross bar.

Based on the design parameters shown above, the best protection performance of the flying cross bar is realized when  $G = 4L_p$ ,  $D_b/D_p = 4$ , and  $KE_b/KE_p = 1/8$ . In this case,  $P/P_o$  is nearly 0.2, which means that flying cross bar incapacitates the penetrator ~80%. To compare this case with the flying plate, the  $P/P_o$  was simulated separately using a flying plate with the same kinetic energy that was  $KE_{plate}/KE_p = 1/8$ ,  $G = 4L_p$ , and  $\theta = 45^\circ$ . While there are several choices in the plate thickness and size, the thickness of plate was assumed to be same as the penetrator diameter and the ratio of length and width of the plate was assumed to be 2:1. In simulation, when the penetrator perforated the plate, the residual depth of penetration in the witness block,  $P/P_o$ , was 0.45. Purely based on the simulation results herein, the flying cross bar seems to be more efficient than the flying plate at a given kinetic energy. However, care has to be taken to interpret this result; Because flying cross *bar* generally just changes shape of the long-rod penetrator while the long-rod penetrator perforates the *plate*, the simulation results can be drastically different depending on the material and fracture models

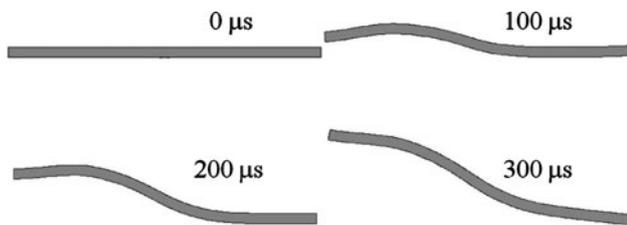


**Fig. 3** Change in depth of penetration as a function of bar diameter  $D_b$  normalized to the diameter of penetrator  $D_p$ . The distances to the witness block  $G$  are **a**  $2L_p$ , **b**  $3L_p$ , and **c**  $4L_p$

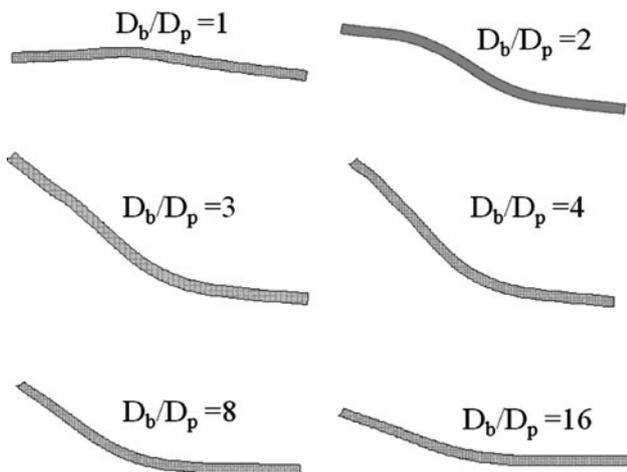
adopted in the simulation and the hitting points of the penetrator.

In some impact conditions with the cross bar, the penetrator is broken with somewhat sharp fracture surfaces

[11], which is possibly due to the tensile fracture with crack propagation. Although the current simulation could not account for such fracture mode, nevertheless, the deformed shapes of the penetrator are presented in Figs. 4, 5 for qualitative understanding of the interaction between the bar and the penetrator. Figure 4 shows the deformed penetrator at varying time lapse after the impact for the case of  $G = 4L_p$ ,  $KE_b/KE_p = 1/32$ , and  $D_b/D_p = 2$ . Since the flying cross bar impacts the mid point of the penetrator at  $45^\circ$ , the tail portion of the penetrator deflects upward and the magnitude of deflection increases as time lapses. 300  $\mu$ s is the time just before the penetrator impacts the witness block. In Fig. 5, the deformed shapes of the penetrator are now shown for varying bar diameter  $D_b/D_p$  at 300  $\mu$ s after the impact. The shapes of residual penetrators are distinguished by three patterns. The shape takes the form of a 'hat' when  $D_b/D_p = 1$ , a reverse-'S' when  $D_b/D_p = 2$ , and 'L' when  $D_b/D_p = 3$  or higher. The magnitude of the lateral displacement of the tail part of the penetrator becomes the largest when  $D_b/D_p = 4$  and decreases thereafter. The decrease of the lateral displacement after  $D_b/D_p = 4$  is due to the decreased bar velocity associated with increased diameter (mass). Thus, the lateral load was insufficient to deform the penetrator in the lateral direction at the given  $KE_b/KE_p$  of  $1/32$ .



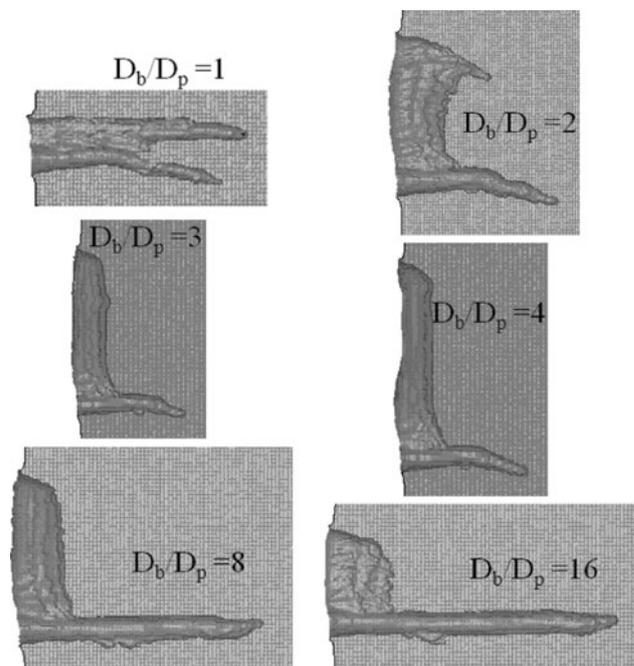
**Fig. 4** Deformed shapes of the residual penetrator at varying time after the impact ( $G = 4L_p$ ,  $KE_b/KE_p = 1/32$ ,  $D_b/D_p = 2$ )



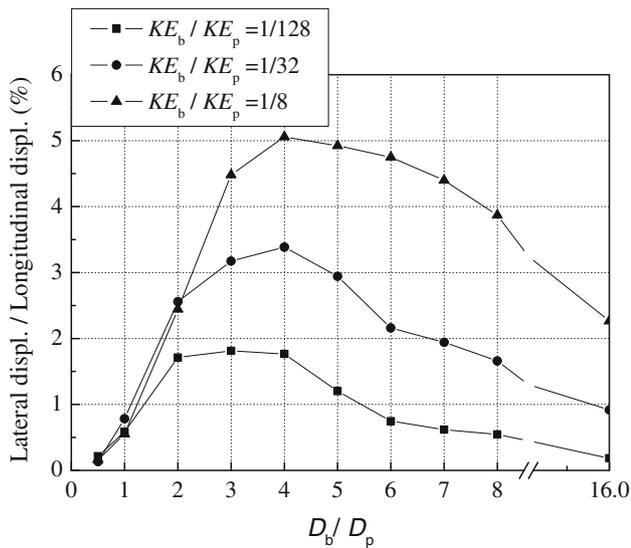
**Fig. 5** Deformed shapes of the residual penetrator at 300  $\mu$ s after the impact for varying  $D_b/D_p$  ratio ( $G = 4L_p$ ,  $KE_b/KE_p = 1/32$ )

The different deformation shapes of the penetrator yield the respective characteristic crater shapes as well as seen in Fig. 6. When  $D_b/D_p = 1$ , the initial penetration hole develops to two similar ones as penetration progresses. In the cases of  $D_b/D_p = 2$  and 3, the shapes of the penetration hole take the forms of 'C' and 'L', respectively. The depth of penetrator is at its minimum at  $D_b/D_p = 3$ , and increases thereafter. When the cross bar is efficient in disturbing the penetrator (when minimum  $P/P_o$  was achieved), the shape of the penetrator takes a form of reverse-'S' (Fig. 5). The same patterns are observed although  $G$  and  $KE_b/KE_p$  ratio vary (not shown).

After correlating the shape of the residual penetrator and crater shape in the witness block to the minimum depth of penetration, now the correlation between the magnitude of the lateral displacement of the penetrator (based on the movement of the centre of mass) and the depth of penetration is pursued. If the penetrator receives a lateral load during its flight, its flight path deviates from the original one and the degree of deviation, i.e., the magnitude of lateral displacement, accumulates until the residual penetrator reaches the witness block. The total magnitude of the lateral displacement of the penetrator by the time it reaches the witness block located at  $G = 4L_p$  has been monitored and the result is shown in Fig. 7 as a function of the bar diameter,  $D_b/D_p$  for varying  $KE_b/KE_p$ . The ordinate is normalized to the longitudinal displacement (translation distance  $4L_p = 600$  mm) for all the cases. The lateral



**Fig. 6** Shapes of the penetration crater at 500  $\mu$ s after the impact for varying  $D_b/D_p$  ratio ( $G = 4L_p$ ,  $KE_b/KE_p = 1/32$ ). The scales of the sub-figures are the same



**Fig. 7** Normalized lateral displacement of the penetrator as a function of bar diameter  $D_b$  normalized to the diameter of penetrator  $D_p$ . The distance to the witness block  $G$  is  $4L_p$

displacement is a rigid body displacement including rotation or averaged displacement. In comparison with the behavior of  $P/P_o$  shown in Fig. 3, the roughly parabolic nature is maintained in Fig. 7 as well. Recall that in Fig. 3, the  $D_b/D_p$  resulting in minimum  $P/P_o$  generally shifted from 1.5 to 4.0 as  $KE_b/KE_p$  increased. In Fig. 7, the  $D_b/D_p$  yielding maximum lateral displacement shifts similarly from 2–4 to 4 as  $KE_b/KE_p$  increases from 1/128 to 1/8. This similarity explains the high correlation of the magnitude of the lateral displacement of the penetrator to the depth of penetration. The critical  $D_b/D_p$  for the minimum  $P/P_o$  and maximum lateral displacement does not coincide exactly because the synergistic influence arising from the characteristic shape, erosion, breakage, and lateral displacement of the residual penetrator, etc., is not accounted for in Fig. 7. When minimum  $P/P_o$  is achieved ( $KE_b/KE_p = 1/8$  and  $D_b/D_p = 4$ ),  $\sim 5\%$  of the maximum lateral displacement with reference to the longitudinal flight distance of  $4L_p$  is observed.

#### 4 Conclusion

Protection performance of a flying cross bar, instead of flying plate, to incapacitate the long-rod penetrator, has been evaluated numerically. The length to diameter ratio,  $L/D$ , of the penetrator was 30 and the velocity was 2.0 km/s. The length of bar was fixed to  $0.5L$  and the velocity of the bar was determined from its mass and given kinetic energy. The bar was assumed to impact the mid point of the penetrator at 45 degree of obliquity. The kinetic energy of flying cross bar considered were 1/128–1/8 times  $KE_p$ . For

each kinetic energy, the diameter of cross bar considered were 0.5–16 times the diameter of the penetrator,  $D_p$ . The distances between penetrator and witness block were  $2L$ – $4L$ .

As  $D_b/D_p$  increases,  $P/P_o$  initially decreases rapidly, but increases back after a minimum  $P/P_o$ . The  $D_b/D_p$  yielding minimum  $P/P_o$  generally shifts from 1.5 to 4.0 as the kinetic energy of the bar  $KE_b/KE_p$  increases. Interestingly, as the kinetic energy of the bar  $KE_b/KE_p$  grows larger, a relatively wider range of  $D_b/D_p$  shows the smaller depth of penetration. As for the influence of  $G$ , the overall trend of  $P/P_o$  in terms of  $D_b/D_p$  for varying  $KE_b/KE_p$  is maintained in similar fashion. However, the  $P/P_o$  decreases with  $G$  significantly at a given condition since the penetrator deforms more with the longer flying time after it is disturbed.

Within the limitations of the current simulation, including the incapability of replicating tensile fracture with crack propagation, simple material models, and assumption of the hitting the midpoint of the penetrator, etc., it was shown that the protection performance of the cross bar could be more efficient than the flying plate, but further rigorous works are necessary to draw out a generalized conclusion on this issue. The magnitude of the lateral displacement of the penetrator is qualitatively well correlated to the resultant depth of penetration in the witness block; other mechanisms such as erosion and breakage of the penetrator are also associated.

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